

Stepper Motor Drive (2 Phase Micro stepping)

SEA 860H

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SEA860H a new high-performance digital stepper Motor driver. It takes 32 bit DPS technology. We use the newest control algorithm to reduce the noise and Vibration in a large scale when the motor works. It has the characteristics of low noise, low vibration, low temperature rising, etc.

Characterstics

1. Power input type: AC 40V ~ 80VAC or DC 60V ~ 110VDC
2. Output current: 2.0A ~ 8.0A
3. Mircosteping:1(1.8°) 1/256 is 51200 step / rev.
4. Protect form :Overheated protect, lock automatic half current, error connect protect
5. Dimensions:100mm×158mm×59mm
6. Weight:<700g.
7. Working environment:Temperature-15 ~ 40°C Humidity<90.

I/O Ports

1. AC Input upto 40VAC & DC Input upto 60VDC
Note: It should exceed 80VAC or 110VDC
2. A+ A-: Stepping motor one winding
3. B+ B-: Stepping motor other winding
4. PUL+ PUL -: Stepping pulse input+5V (Rising edge effective, rising edge duration >10μS)
5. DIR + DIR-:Stepping motor direction input, voltage level touched off, high towards, low reverse
6. ENA+ ENA-: motor free

Switch Choice

("ON=0,OFF=1")

Microstepping Setting

SW5SW6SW7SW8	MICRO STEP
0 0 0 0	DEFAULT
1 0 0 0	4
0 1 0 0	8
1 1 0 0	16
0 0 1 0	32
1 0 1 0	64
0 1 1 0	128
1 1 1 0	256
0 0 0 1	5
1 0 0 1	10
0 1 0 1	20
1 1 0 1	25
0 0 1 1	40
1 0 1 1	50
0 1 1 1	100
1 1 1 1	200

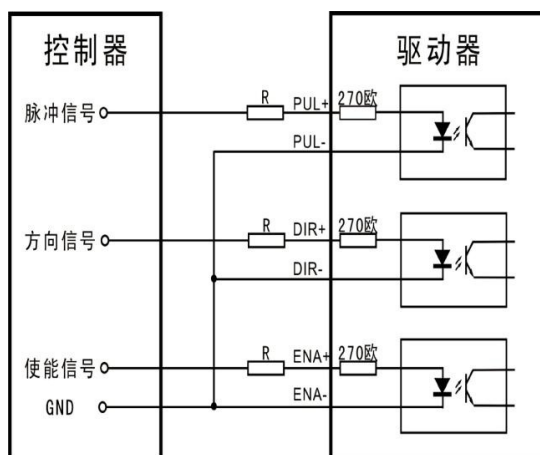
Current Setting

SW1SW2SW3	RMS	Peek
0 0 0	2.00A	2.4 0A
1 0 0	2.57A	3.0 8A
0 1 0	3.14A	3.7 7A
1 1 0	3.71A	4.4 5A
0 0 1	4.28A	5.1 4A
1 0 1	4.86A	5.8 3A
0 1 1	5.43A	6.5 2A
1 1 1	6.00A	8.0 0A

Wiring Diagram

Controller

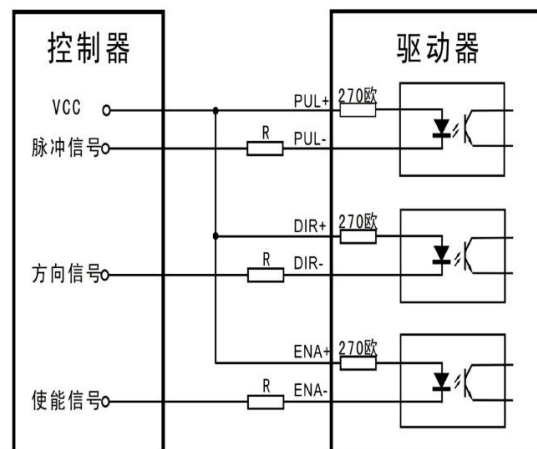
Drive



Common Cathod

Controller

Drive



signal amplitude	External current limiting resistor
5 V	without
12 V	680Ω
24 V	1.8KΩ

Mechanical Specifications

